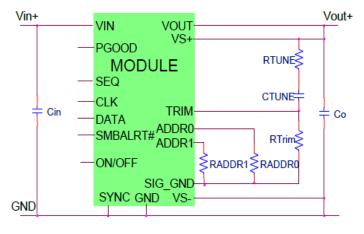


6A Digital Pico SlimLynx Open Frame: Non-Isolated DC-DC Modules

3V_{dc} -14.4V_{dc} input; 0.45V_{dc} to 5.5V_{dc} output; 6A Output Current





Description

The OmniOnPower™ 6A Digital Pico SlimLynx Open Frame power modules are non-isolated dc-dc converters that can deliver up to 6A of output current. These modules operate over a wide range of input voltage ($V_{IN} = 3V_{dc}-14.4V_{dc}$) and provide a precisely regulated output voltage from 0.45V_{dc} to 5.5V_{dc}, programmable via an external resistor and PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, over current and over temperature protection. The PMBus interface supports a range of commands to both control and monitor the module. The module also includes the Tunable Loop feature that allows the user to optimize the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.

Applications

- Distributed power architectures
- Intermediate bus voltage applications
- Telecommunications equipment
- Servers and storage applications
- Networking equipment
- Industrial equipment

See footnotes on page 2



Features

- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863.
- Compliant to REACH Directive (EC) No 1907/2006
- Compliant to IPC-9592 (September 2008), Category 2, Class II
- Ultra low height design for very dense power applications.
- Small size: 12.2 mm x 12.2 mm x 2.8 mm (Max) (0.48 in x 0.48 in x 0.110 in)
- Output voltage programmable from 0.6V_{dc} to 5.5V_{dc} via external resistor. Digitally adjustable down to 0.45V_{dc}
- Wide Input voltage range (3V_{dc}-14.4V_{dc})
- Wide operating temperature range [-40°C to 85°
 C]. See derating curves
- DOSA approved footprint
- Digital interface through the PMBus™ # protocol

- Tunable Loop to optimize dynamic output voltage response
- Flexible output voltage sequencing EZ-SEQUENCE
- Power Good signal
- Remote On/Off
- Fixed switching frequency with capability of external synchronization
- Output overcurrent protection (non-latching)
- Overtemperature protection
- Ability to sink and source current
- Compatible in a Pb-free or SnPb reflow environment
- ANSI/UL* 62368-1 and CAN/CSA† C22.2 No. 62368-1 Recognized, DIN VDE‡0868-1/A11:2017 (EN62368-1:2014/A11:2017)
- ISO** 9001 and ISO 14001 certified manufacturing facilities

FOOTNOTES

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^{*} UL is a registered trademark of Underwriters Laboratories, Inc.

[†]CSA is a registered trademark of Canadian Standards Association.

[‡] VDE is a trademark of Verband Deutscher Elektrotechniker e.V.

 $[\]ensuremath{^{**}}$ ISO is a registered trademark of the International Organization of Standards



Technical Specifications

Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage	All	V _{IN}	-0.3	15	V
Continuous		V IN	0.5	15	v
SEQ, SYNC, VS+	All			7	V
CLK, DATA, SMBALERT#	All			3.6	V
Operating Ambient Temperature	All	т	/0	O.F.	°C
(see Thermal Considerations section)	All	T _A	-40	85	٠
Storage Temperature	All	T_{stg}	-55	125	°C

Electrical Specifications

Unless otherwise indicated, specifications apply overall operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V_{IN}	3	_	14.4	V_{dc}
Maximum Input Current $(V_{IN} = 3V \text{ to } 14V, I_O = I_{O, max})$	All	I _{IN,max}			6	A _{dc}
Input No Load Current	$V_{O,set}$ = 0.6 V_{dc}	$I_{\text{IN,No load}}$		25		mA
$(V_{IN} = 12V_{dc}, I_0 = 0, module enabled)$	$V_{O,set} = 5.5V_{dc}$	$I_{\text{IN,No load}}$		130		mA
Input Stand-by Current (V _{IN} = 12V _{dc} , module disabled)	All	I _{IN,stand-by}		9		mA
Inrush Transient	All	l²t			1	A ² s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1µH source impedance; V _{IN} =0 to 14V, I _O =I _{O, max} ; See Test Configurations)	All			50		mA _{p-p}
Input Ripple Rejection (120Hz)	All			-55	-	dB
Output Voltage Set-point (with 0.1% tolerance for external resistor used to set output voltage)	All	V _{O, set}	-1.0		+1.0	% V _{O, set}
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	$V_{\text{O, set}}$	-3.0	_	+3.0	% V _{O, set}
Adjustment Range (selected by an external resistor) (Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section)	All	Vo	0.6		5.5	V_{dc}
PMBus Adjustable Output Voltage Range	All	$V_{\text{O, adj}}$	-25	0	+25	$\%$ $V_{O, set}$
PMBus Output Voltage Adjustment Step Size	All		0.4			$\%$ $V_{O, set}$
Remote Sense Range	All				0.5	V _{dc}
Output Regulation (for $V_0 \ge 2.5V_{dc}$)						
Line (V _{IN} =V _{IN} , min to V _{IN} , max)	All			_	+0.4	$\%$ $V_{O, set}$
Load (I _O =I _{O, min} to I _{O, max})	All			_	10	mV
Output Regulation (for $V_0 < 2.5V_{dc}$)						
Line $(V_{IN}=V_{IN, min} \text{ to } V_{IN, max})$	All			_	5	mV
Load (Io=Io, min to Io, max)	All			_	10	mV
Temperature ($T_{ref}=T_{A, min}$ to $T_{A, max}$)	All				0.4	$\%$ $V_{O, set}$



Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Input Noise on nominal input at 25°C						
$(V_{IN}=V_{IN}, nom and I_O=I_{O, min} to I_{O, max}C_{in}=1x47nF(0402) or$						
equivalent, $2x22uF(1210)$ ceramic capacitors or equivalent and Peak-to-Peak (Full Bandwidth) for all V_o	A 11			760		Δ
Output Ripple and Noise on nominal output at 25°C	All		-	360		mA _{p-kpk}
$(V_{IN}=V_{IN, nom} \text{ and } I_O=I_{O, min} \text{ to } I_{O, max}C_o=2x47nF(0402) \text{ or}$						
equivalent, 2x47uF (1210) or equivalent ceramic						
capacitors on output and 1x47nF(0402) or equivalent, 2x22uF(1210) ceramic capacitors or equivalent and						
470uF,16V electrolytic) on input						
Peak-to-Peak (Full bandwidth) V₀≤1.2V₀				30 ²		mV_{pk-pk}
Peak-to-Peak (Full bandwidth) V _o >1.2V _o	All			3%V ₀ ²		mV_{pk-pk}
RMS (Full bandwidth) for all V _o	All			20 ²		mV_{rms}
External Capacitance ¹						
Without the Tunable Loop					0) / / [_
ESR ≥ 1 mΩ	All	C _{O, max}	1 X 47		2 X 47	μF
With the Tunable Loop			0) / / [1000	_
ESR ≥ 0.15 mΩ	All	Co, max	2 X 47		1000	μF –
ESR ≥ 10 mΩ	All	C _{O, max}			5000	μF
Output Current (in either sink or source mode)	All	lo	0		6	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	I _{O, lim}		130		% I _{o,max}
Output Short-Circuit Current (Vo≤250mV) (Hiccup Mode)	All	I _O , s/c		1.3		A_{rms}
Efficiency	$V_{O,set} = 0.6V_{dc}$	η		70.9		%
V_{IN} = 12 V_{dc} , T_A =25°C	V _{0,set} = 0.0 V _{dc}	•		81.8		%
$I_O=I_{O, max}$, $V_O=V_{O, set}$	$V_{O,set} = 1.2 V_{dc}$ $V_{O,set} = 1.8 V_{dc}$	η		85.6		%
	$V_{O,set} = 1.8 V_{dc}$ $V_{O,set} = 2.5 V_{dc}$	η		88.2		%
	$V_{O,set} = 2.3 V_{dc}$	η		89.7		% %
	$V_{O,set} = 5.0 V_{dc}$ $V_{O,set} = 5.0 V_{dc}$	η		91.8		%
Christoping Fraguency		η f _{sw}				
Switching Frequency Frequency Synchronization	All All	Isw	_	800	_	kHz
Synchronization Frequency Range	All		760	800	840	kHz
High-Level Input Voltage	All	V _{IH}	2	000	070	V
Low-Level Input Voltage	All	VIH			0.4	V
Input Current, SYNC	All	I _{SYNC}			100	nA
Minimum Pulse Width, SYNC	All	t _{SYNC}	100		-	ns
Maximum SYNC rise time	All	t _{sync_sh}	100			ns

¹ External capacitors may require using the new Tunable Loop feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop section for details.

General Specifications

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (I_0 =0.8 $I_{0, max}$, T_A =40°C) Telcordia Issue 3 Method 1 Case 3	All		72,960,488		Hours
Weight			0.8(0.028)		g (oz.)

² Exception noted in the ERRATA near the end of this datasheet



Feature Specifications

Unless otherwise indicated, specifications apply overall operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Тур	Max	Unit
On/Off Signal Interface	Device	Symbol	М	Jyp	Max	Offic
$(V_{IN}=VI_{N, min} \text{ to } V_{IN, max}; \text{ open collector or}$						
equivalent,						
Signal referenced to GND)						
Device Code with no suffix – Negative Logic (See						
Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)					_	
Input High Current	All	I _{IH}	_	_	1	mA
Input High Voltage	All	V _{IH}	2		$V_{\text{IN, max}}$	V_{dc}
Logic Low (Module ON)						
Input low Current	All	I _{IL}		_	50	μΑ
Input Low Voltage	All	V_{IL}	-0.2	_	0.6	V_{dc}
Turn-On Delay and Rise Times						
$(V_{IN}=V_{IN, nom}, I_O=I_{O, max}, V_O \text{ to within } \pm 1\% \text{ of steady state})$						
Case 1: On/Off input is enabled and then input						
power is applied (delay from instant at which	All	T_{delay}		0.9		msec
$V_{IN} = V_{IN, min}$ until $V_o = 10\%$ of $V_{o, set}$)						
Case 2: Input power is applied for at least one						
second and then the On/Off input is enabled		_				
(delay from instant at which Von/Off is enabled	All	T_{delay}	_	0.8	_	msec
until $V_0 = 10\%$ of $V_{0, set}$)						
Output voltage Rise time (time for V _o to rise						
from 10% of V _o , set to 90% of V _o , set)	All	T_{rise}	_	2		msec
Output voltage overshoot						
$(T_A = 25^{\circ}\text{C V}_{IN} = V_{IN, min} \text{ to } V_{IN, max}, I_O = I_O, min \text{ to } I_{O, max})$					3	0/ \/
					٥	$\%$ $V_{O, set}$
With or without maximum external capacitance						
Over Temperature Protection	A 11	_		170		°C
(See Thermal Considerations section)	All	T_{ref}		130		C
PMBus Over Temperature Warning Threshold *	All	T _{WARN}		120		°C
Tracking Accuracy (Power-Up: 2V/ms)	All	V _{SEQ} –V _o		100		mV
(Power-Down: 2V/ms)		-				
$(V_{IN, min} \text{ to } V_{IN, max}; I_{O, min} \text{ to } I_{O, max} V_{SEQ} < V_O)$	All	$V_{SEQ} - V_o$		100		mV
Input Undervoltage LOCKOUT						
Turn-on Threshold	All			2.75		V_{dc}
Turn-off Threshold	All			2.5		V_{dc}
Hysteresis	All			0.25		V_{dc}
PMBus Adjustable Input Under Voltage Lockout	All		2.5		14	V_{dc}
Thresholds						as
Resolution of Adjustable Input Under Voltage	All				500	mv
Threshold						
PGOOD (Power Good) Signal Interface Open Drain, V _{supply} ≤ 5V _{DC}						
Overvoltage threshold for PGOOD ON	All			108		%\/_
Overvoltage threshold for PGOOD OFF	All			110		%V _{O, set} %V _{O, set}
Undervoltage threshold for PGOOD ON	All			92		%V _{O, set}
Undervoltage threshold for PGOOD OFF	All			90		%V _{O, set}
Pulldown resistance of PGOOD pin	All				50	Ω
Sink current capability into PGOOD pin	All				5	mA

 $^{^*\, {\}sf Over \, temperature \, Warning \, - \, Warning \, may \, not \, activate \, before \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, and \, unit \, may \, shutdown \, before \, warning \, alarm \, alar$



Digital Interface Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics						
Input High Voltage (CLK, DATA)		V _{IH}	2.1		3.6	V
Input Low Voltage (CLK, DATA)		V _{IL}			0.8	V
Input high level current (CLK, DATA)		I _{IH}	-10		10	μA
Input low level current (CLK, DATA)		I _{IL}	-10		10	μA
Output Low Voltage (CLK, DATA, SMBALERT#)	I _{out} =2mA	V _{OL}			0.4	V
Output high level open drain leakage current (DATA, SMBALERT#)	V _{OUT} =3.6V	I _{ОН}	0		10	μΑ
Pin capacitance		Co		0.7		рF
PMBus Operating frequency range	Slave Mode	F _{PMB}	10		400	kHz
Data hold time	Receive Mode	+	0			ns
Data noid time	Transmit Mode	t _{hd:dat}	300			
Data setup time		t _{su:DAT}	250			ns
Measurement System Characteristics						
Read delay time		$t_{\scriptscriptstyle DLY}$	153	192	231	μs
Output current measurement range		I _{RNG}	0		9	Α
Output current measurement resolution		I _{RES}	62.5			mA
Output current measurement gain accuracy at 25°C (with l _{OUT,CORR})		I _{ACC}		±5		%
Output current measurement offset		I _{OFST}		0.1		Α
V _{out} measurement range		$V_{OUT(rng)}$	0		5.5	V
V _{OUT} measurement resolution		V _{OUT(res)}		15.625		mV
V _{out} measurement accuracy		V _{OUT(ACC)}	-15		15	%
V _{out} measurement offset		V _{OUT(ofst)}	-3		3	%
V _{IN} measurement range		V _{IN(rng)}	3		14.4	V
V _{IN} measurement resolution		V _{IN(res)}		32.5		mV
V _{IN} measurement accuracy		V _{IN(ACC)}	-15		15	%



Characteristic Curves

The following figures provide typical characteristics for the 6A Digital Pico SlimLynx at 0.6V₀ and 25°C.

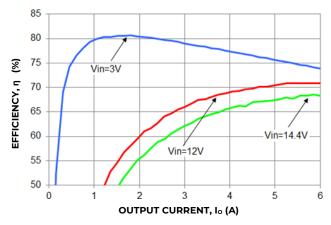


Figure 1. Converter Efficiency verses output current

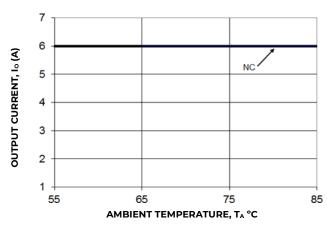


Figure 2. Derating Output Current verses Ambient Temperature and Airflow.

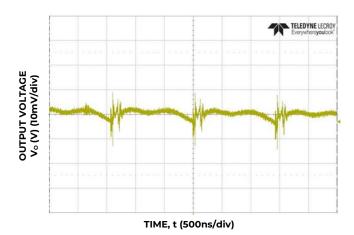


Figure 3. Typical output ripple and noise (C_0 =2x47 μ F ceramic, V_{IN} = 12V, I_o = $I_{o,max}$).

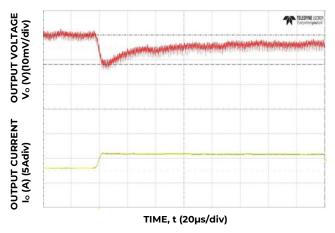


Figure 4. Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, C_{out} = 3x47uF + 3x330uF, C_{Tune} =10nF, R_{Tune} =300 Ω

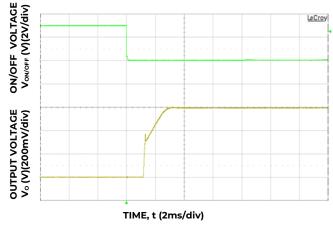


Figure 5. Typical Start-up Using On/Off Voltage (Io = Io,max).

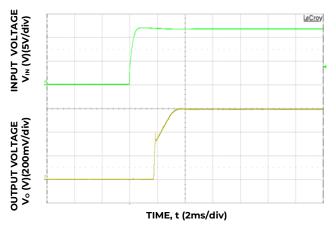


Figure 6. Typical Start-up Using Input Voltage ($V_{IN} = 12V$, $I_o = I_{o,max}$).



Characteristic Curves (continued)

The following figures provide typical characteristics for the 6A Analog Pico SlimLynx at 1.2V_o and 25°C.

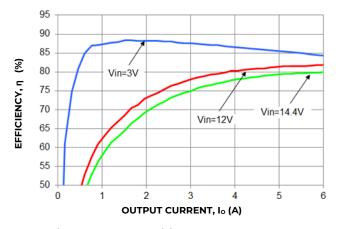


Figure 7. Converter Efficiency versus Output Current.

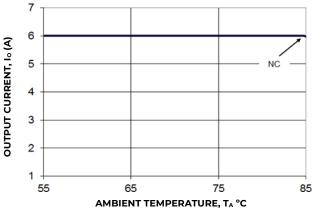


Figure 8. Derating Output Current versus Ambient Temperature and Airflow.



Figure 9. Typical output ripple and noise (C_0 =2x47 μ F ceramic, V_{IN} = 12V, $I_{O=I_{O,max}}$).

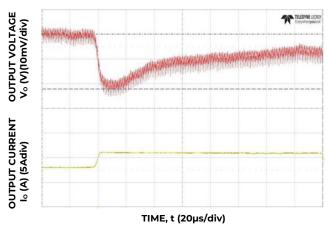


Figure 10. Transient Response to Dynamic Load Change from 50% to 100% at 12V $_{in}$, C $_{out}$ =3x47uF+2x330uF, C $_{Tune}$ =5600pF, R $_{Tune}$ =300 Ω

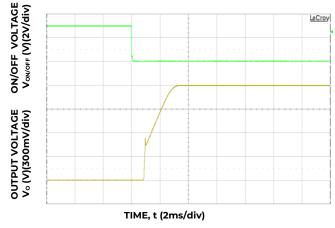


Figure 11. Typical Start-up Using On/Off Voltage (Io = Io,max).

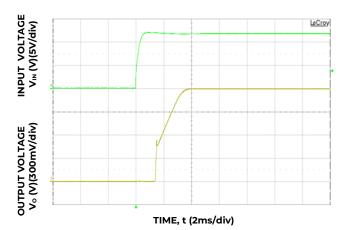


Figure 12. Typical Start-up Using Input Voltage $(V_{IN} = 12V, I_o = I_{o,max})$.



Characteristic Curves (continued)

The following figures provide typical characteristics for the 6A Analog Pico SlimLynx at 1.8Vo and 25°C.

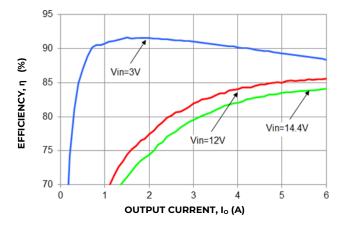


Figure 13. Converter Efficiency versus Output Current.

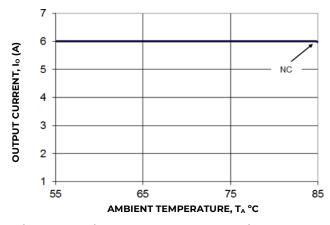


Figure 14. Derating Output Current versus Ambient Temperature and Airflow..

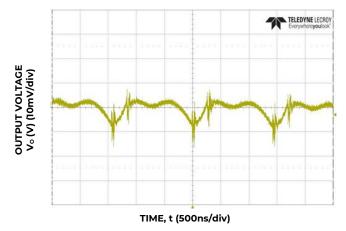


Figure 15. Typical output ripple and noise ($C_o=2x47\mu F$ ceramic, $V_{IN}=12V,\ I_o=I_{o,max_I}$).

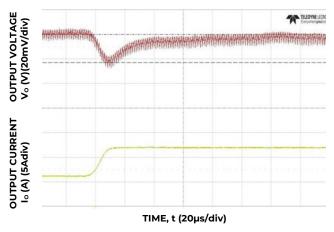


Figure 16. Transient Response to Dynamic Load Change from 50% to 100% at $12V_{in}$, C_{out} =3x47uF+1x330uF, C_{Tune} =3900pF, R_{Tune} =300

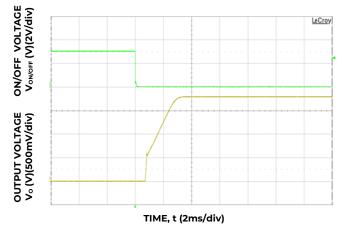


Figure 17. Typical Start-up Using On/Off Voltage ($I_o = I_{o,max}$).

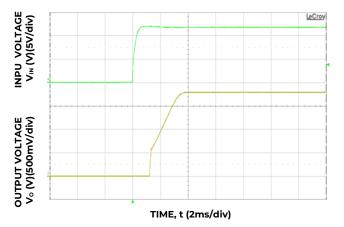


Figure 18. Typical Start-up Using Input Voltage $(V_{IN} = 12V, I_o = I_{o,max})$.



Characteristic Curves (continued)

The following figures provide typical characteristics for the 6A Analog Pico SlimLynx at 2.5V_o and 25°C.

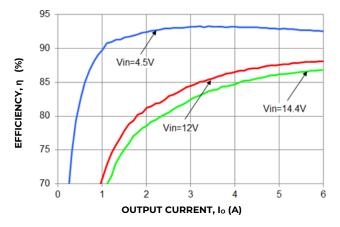


Figure 19. Converter Efficiency versus Output Current.

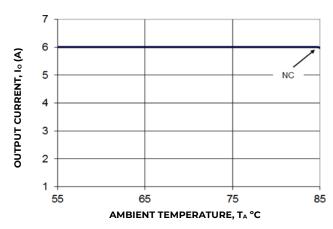


Figure 20. Derating Output Current versus Ambient Temperature and Airflow.



Figure 21. Typical output ripple and noise $(C_0=2x47\mu F \text{ ceramic}, V_{IN}=12V, I_o=I_{o,max_i}).$

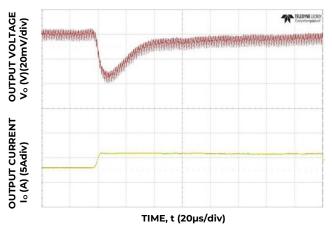


Figure 22. Transient Response to Dynamic Load Change from 50% to 100% at 12V $_{in}$, C $_{out}$ =3x47uF+1x330uF, C $_{Tune}$ =2200pF, R $_{Tune}$ =300 Ω

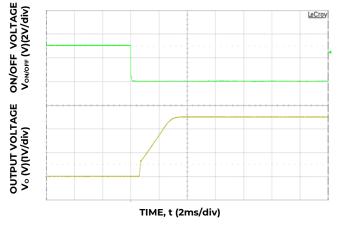


Figure 23. Typical Start-up Using On/Off Voltage ($I_o = I_{o,max}$).

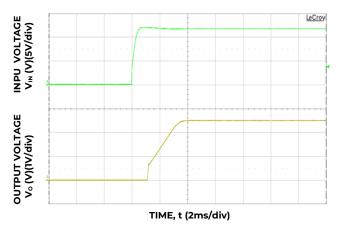


Figure 24. Typical Start-up Using Input Voltage (V_{IN} = 12V, I_o = $I_{o,max}$).



Characteristic Curves (continued)

The following figures provide typical characteristics for the 6A Analog Pico SlimLynx at 3.3V_o and 25°C.

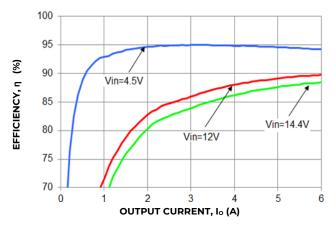


Figure 25. Converter Efficiency versus Output Current.

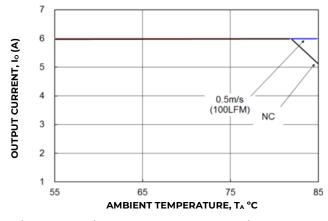


Figure 26. Derating Output Current versus Ambient Temperature and Airflow.

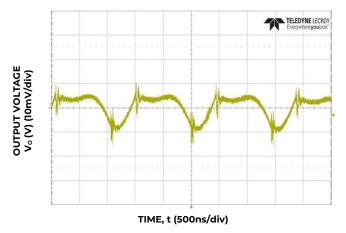


Figure 27. Typical output ripple and noise $(C_0=2x47\mu F \text{ ceramic}, V_{IN}=12V, I_0=I_{0,max}).$

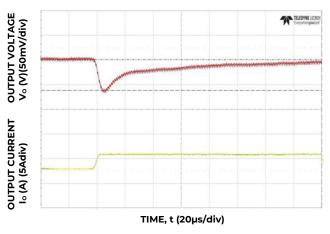


Figure 28. Transient Response to Dynamic Load Change from 50% to 100% at 12V_{in}, C_{out}=5x47uF, C_{Tune}=1800pF, R_{Tune}=300

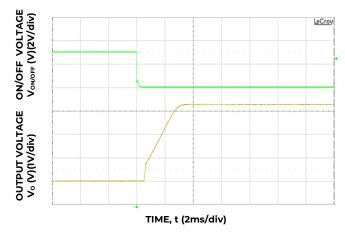


Figure 29. Typical Start-up Using On/Off Voltage ($I_o = I_{o,max}$).

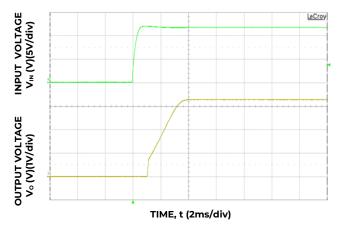


Figure 30. Typical Start-up Using Input Voltage $(V_{IN} = 12V, I_o = I_{o,max})$.



Characteristic Curves (continued)

The following figures provide typical characteristics for the 6A Analog Pico SlimLynx at 5Vo and 25°C.

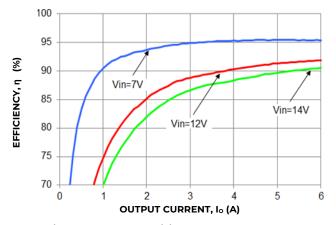


Figure 31. Converter Efficiency versus Output Current.

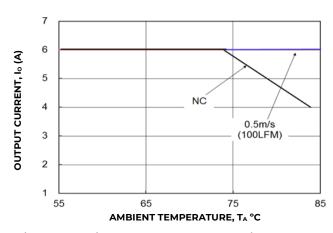


Figure 32. Derating Output Current versus Ambient Temperature and Airflow.

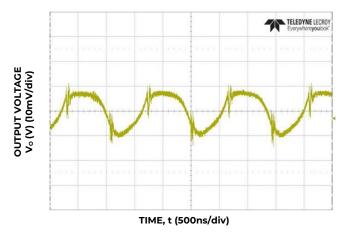


Figure 33. Typical output ripple and noise ($C_0=2x47\mu F$ ceramic, $V_{IN}=12V$, $I_0=I_{o,max}$).

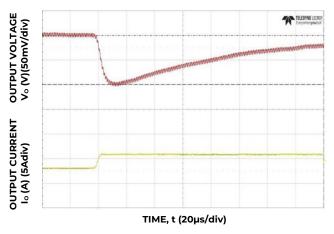


Figure 34. Transient Response to Dynamic Load Change from 50% to 100% at 12V_{in}, C_{out}=5x47uF, C_{Tune}=1800pF, R_{Tune}=300Ω.

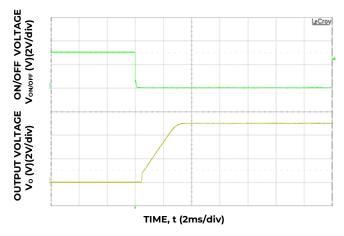


Figure 35. Typical Start-up Using On/Off Voltage ($I_0 = I_{o,max}$).

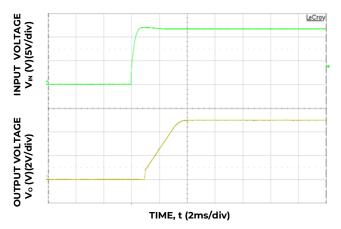


Figure 36. Typical Start-up Using Input Voltage (V_{IN} = 12V, I_o = $I_{o,max}$).



Design Considerations

Input Filtering

The 6A Digital Pico SlimLynx Open Frame module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 37 shows the input ripple voltage for various output voltages at 6A of load current with 1x22 μF or 2x22 μF ceramic capacitors and an input of 12V.

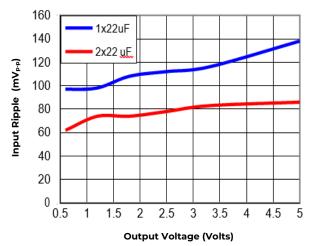


Figure 37. Input ripple voltage for various output voltages with 1x22 μF or 2x22 μF ceramic capacitors at the input (6A load).
Input voltage is 12V. Scope BW Limited to 20MHz

Output Filtering

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with 3x0.047 μF ceramic and 2x47 μF ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 38 provides output ripple information, measured with a scope with its Bandwidth limited to 20MHz for different external capacitance values at various Vo and a full load current of 6A. For stable operation of the

module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable Loop feature described later in this data sheet.

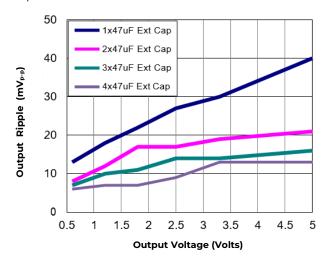


Figure 38. Output ripple voltage for various output voltages with external 1x47uF, 2x47 μ F, 3x47 μ F, or 4x47 μ F ceramic capacitors at the output (6A load). Input voltage is 12V. Scope BW Limited to 20MHz

Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL ANSI/UL* 62368-1 and CAN/CSA* C22.2 No. 62368-1 Recognized, DIN VDE 0868-1/A11:2017 (EN62368-1:2014/A11:2017)

For the converter output to be considered meeting the Requirements of safety extra-low voltage (SELV) or ES1, the input must meet SELV/ES1 requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a fast acting fuse (e.g. ABC Bussmann, 250V) with a maximum rating of 20A in the positive input lead.



Analog Feature Descriptions

Remote On/Off

The module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the two ON/OFF inputs:

- Module ON/OFF can be controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF can be controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF can be controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

Analog On/Off

The 6A Digital Pico SlimLynx Open Frame power modules feature an On/Off pin for remote On/Off operation. With Negative Logic On/Off operation, (no device code suffix, see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. For either On/Off logic option, leaving the On/Off pin disconnected will turn the module ON when input voltage is present.

For negative logic On/Off modules, the circuit configuration is shown in Fig. 40. The On/Off pin should be pulled high with an external pull-up resistor. When transistor Q2 is in the OFF state, the On/Off pin is pulled high, transistor Q32 is turned ON. This pulls the internal ENABLE low and the module is OFF. To turn the module ON, Q2 is turned ON pulling the On/Off pin low, turning transistor Q32 OFF, which results in the PWM Enable pin going high.

Digital On/Off

Please see the Digital Feature Descriptions section

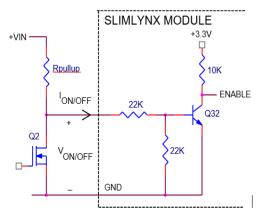


Figure 39. Circuit configuration for using negative On/Off logic.

Monotonic Start-up and Shutdown

The module has monotonic start-up and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

Startup into Pre-biased Output

The module can start into a prebiased output as long as the prebias voltage is 0.5V less than the set output voltage.

Analog Output Voltage Programming

The output voltage of the module is programmable to any voltage from 0.6dc to $5.5 V_{\rm dc}$ by connecting a resistor between the Trim and SIG_GND pins of the module. Certain restrictions apply on the output voltage set point depending on the input voltage. These are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 40. The Upper Limit curve shows that for output voltages lower than 1V, the input voltage must be lower than the maximum of 14.4V. The Lower Limit curve shows that for output voltages higher than 0.6V, the input voltage needs to be larger than the minimum of 3V.

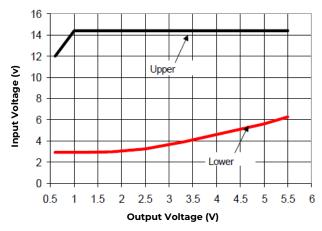


Figure 40. Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.



Analog Output Voltage Programming (continued)

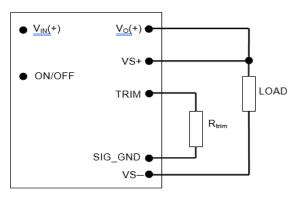


Figure 41. Circuit configuration for programming output voltage using an external resistor.

Caution – Do not connect SIG_GND to GND elsewhere in the layout

Without an external resistor between Trim and SIG_GND pins, the output of the module will be 0.6V_{dc}.To calculate the value of the trim resistor, R_{trim} for a desired output voltage, should be as per the following equation:

 R_{trim} is the external resistor in $k\Omega$ V_o is the desired output voltage.

Table 1 provides R_{trim} values required for some

V o, set (V)	R_{trim} (K Ω)
0.6	Open
0.9	40
1.0	30
1.2	20
1.5	13.33
1.8	10
2.5	6.316
3.3	4.444
5.0	2.727

common Table 1 output voltages.

Digital Output Voltage Adjustment

Please see the Digital Feature Descriptions section.

Remote Sense

Power

The power module has a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-). The voltage drop between the sense pins and the V_{OUT} and GND pins of the module should not exceed 0.5V.

Analog Voltage Margining

Output voltage margining can be implemented in the module by connecting a resistor, R_{margin-up}, from the Trim pin to the ground pin for margining-up the output voltage and by connecting a resistor, R_{margin-down}, from the Trim pin to output pin for margining-down. Figure 42 shows the circuit configuration for output voltage margining. The POL Programming Tool, available at **omnionpower.com** under the Downloads section, also calculates the values of R_{margin-up} and R_{margin-down} for a specific output voltage and % margin. Please consult your local OmniOn _______ Critical

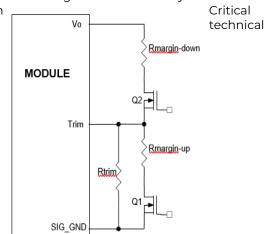


Figure 42. Circuit Configuration for margining Output voltage.

representative for additional details.



Digital Output Voltage Adjustment

Please see the Digital Feature Descriptions section.

Output Voltage Sequencing

The power module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

The

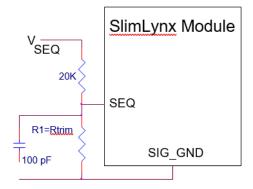


Figure 43. Circuit showing connection of the sequencing signal to the SEQ pin

voltage applied to the SEQ pin should be scaled down by the same ratio as used to scale the output voltage down to the reference voltage of the module. This is accomplished by an external resistive divider connected across the sequencing voltage before it is fed to the SEQ pin as shown in Fig. 43. In addition, a

Output Voltage Sequencing (continued)

small capacitor (suggested value 100pF) should be connected across the lower resistor R1.

For all SlimLynx modules, the minimum recommended delay between the ON/OFF signal and the sequencing signal is 10ms to ensure that the module output is ramped up according to the sequencing signal. This ensures that the module soft-start routine is completed before the sequencing signal is allowed to ramp up.

When the scaled down sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5V/msec during power-up or power-down.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their set- point voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

Note that in all digital SlimLynx series of modules, the PMBus Output Undervoltage Fault will be tripped when sequencing is employed. This will be detected using the STATUS_WORD and STATUS_VOUT PMBus commands. In addition, the SMBALERT# signal will be asserted low as occurs for all faults and warnings. To avoid the module shutting down due to the Output Undervoltage Fault, the module must be set to continue operation without interruption as the response to this fault (see the description of the PMBus command VOUT_UV_FAULT_RESPONSE for additional information).

Overcurrent Protection

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry and can endure current limiting continuously. At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range.

Digital Adjustable overcurrent Warning

Please see the Digital Feature Descriptions section.

Overtemperature Protection

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 150° C(typ) is exceeded at the thermal reference point T_{ref} . Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

Digital Temperature Status via PMBus

Please see the Digital Feature Descriptions section.

Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.



Synchronization (continued)

Synchronization can be done by using the external signal applied to the SYNC pin of the module as shown in Fig. 44, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency. If synchronization is not being used, connect the SYNC pin to GND.

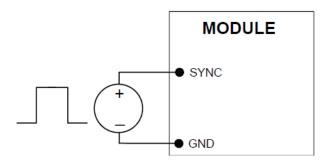


Figure 44. External source connections to synchronize switching frequency of the module.

Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

Tunable Loop

The module has a feature that optimizes transient response of the module called Tunable Loop.

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 38) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The Tunable Loop allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable Loop is implemented by connecting a series R-C between the VS+ and TRIM pins of the module, as shown in Fig. 45. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

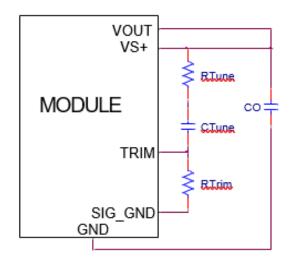


Figure. 45. Circuit diagram showing connection of R_{TUNE} and C_{TUNE} to tune the control loop of the module

Recommended values of R_{TUNE} and C_{TUNE} for different output capacitor combinations are given in Table 2. Table 2 shows the recommended values of R_{TUNE} and C_{TUNE} for different values of ceramic output capacitors up to 1000uF that might be needed for an application to meet output ripple and noise requirements. Selecting R_{TUNE} and C_{TUNE} according to Table 2 will ensure stable operation of the module.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of R_{TUNE} and C_{TUNE} in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 3A to 6A step change (50% of full load), with an input voltage of 12V.

Please contact your OmniOn Critical Power technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

C。	3x47μF	4x47μF	6x47μF	10x47µF	20x47μF
R_{TUNE}	300	300	300	300	300
C_{TUNE}	560pF	820pF	1200pF	2700pF	5600pF

Table 2. General recommended values of of R_{TUNE} and C_{TUNE} for V_{in} =12V and various external ceramic capacitor combinations



Tunable Loop (continued)

V _o	5V	3.3V	2.5V	1.8V	1.2V	0.6V
С。	5x47µf Ceramic	5x47µF Ceramic	3x47µF+ 1x330 µF Polymer	3x47µF+ 1x330µF Polymer	3x47µF+ 2x330µF Polymer	3x47µF+ 3x330µF Polymer
R _{TUNE}	300	300	300	300	300	300
C _{TUNE}	1800pF	1800pF	2200pF	3900pF	5600pF	10nF
ΔV	47mV	45mV	32mV	24mV	22mV	12mV

Table 3. Recommended values of R_{TUNE} and C_{TUNE} to obtain transient deviation of 2% of V_{out} for a 6A step load with V_{in} =12V.

Note: The capacitors used in the Tunable Loop tables are 47 μ F/2 m Ω ESR ceramic and 330 μ F/9 m Ω ESR polymer capacitors.

Digital Feature Descriptions

PMBus Interface Capability

The 6A Digital Pico SlimLynx Open Frame power modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from www.pmbus.org.. The modules support a subset of version 1.1 of the specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

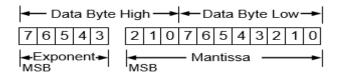
All communication over the module PMBus interface must support the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module.

The module also supports the SMBALERT# response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

PMBus Data Format

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by Value = Mantissa x 2 Exponent

PMBus Addressing

The power module can be addressed through the PMBus using a device address. The module has 64 possible addresses (0 to 63 in decimal) which can be set using resistors connected from the ADDRO and ADDR1 pins to SIG_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specifications and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (1% tolerance resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

Digit	Resistor Value (KΩ)
0	10
1	15.4
2	23.7
3	36.5
4	54.9
5	84.5
6	130
7	200

The user must know which I²C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, **SMBus.org**



PMBus Addressing (continued)

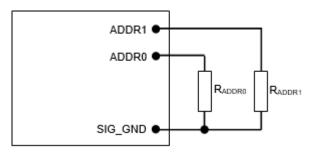


Figure 46. Circuit showing connection of resistors used to set the PMBus address of the module.

PMBus Enabled On/Off

The module can also be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON_OFF_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

- 0: Output is disabled
- 1: Output is enabled

This module uses the lower five bits of the ON_OFF_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r/w	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	1

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

Bit ValueAction					
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin				
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.				

CMD: The CMD bit controls how the device responds to the OPERATION command.

Bit Val	ue Action
0	Module ignores the ON bit in the OPERATION
	command
7	Module responds to the ON bit in the
	OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

Bit Value	Action
0	Module ignores the analog ON/OFF pin, i.e.ON/OFF is only controlled through the PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit

PMBus Adjustable Soft Start Rise Time

The soft start rise time can be adjusted in the module via PMBus. When setting this parameter, make sure that the charging current for output capacitors can be delivered bythe module in addition to any load current to avoid nuisance tripping of the overcurrent protection circuitry during startup. The TON_RISE command sets the rise time in ms, and allows choosing soft start times between 600µs and 9ms, with possible values listed in Table 5. Note that the exponent is fixed at -4 (decimal) and the upper two bits of the mantissa are also fixed at 0.

Rise Time	Exponent	Mantissa
600µs	11100	00000001010
900µs	11100	00000001110
1.2ms	11100	00000010011
1.8ms	11100	00000011101
2.7ms	11100	00000101011
4.2ms	11100	00001000011
6.0ms	11100	00001100000
9.0ms	11100	00010010000

Output Voltage Adjustment Using the PMBus

The VOUT_SCALE_LOOP parameter is important for a number of PMBus commands related to output voltage trimming, margining, over/under voltage protection and the PGOOD thresholds. The output voltage of the module is set as the combination of the voltage divider formed by R_{Trim} and a $20 k\Omega$ upper divider resistor inside the module, and the internal reference voltage of the module. The reference voltage VREF is nominally set at 600mV, and the output regulation voltage is then given by

$$V_{OUT} = \frac{20000 + RTrim}{RTrim} X V_{REF}$$



Output Voltage Adjustment Using the PMBus (continued)

Hence the module output voltage is dependent on the value of RTrim which is connected external to the module. The information on the output voltage divider ratio is conveyed to the module through the VOUT_SCALE_LOOP parameter which is calculated as follows:

VOUT_SCALE_LOOP =
$$\frac{RTrim}{20000 + RTrim}$$

The VOUT_SCALE_LOOP parameter is specified using the "Linear" format and two bytes. The upper five bits [7:3] of the high byte are used to set the exponent which is fixed at –9 (decimal). The remaining three bits of the high byte [2:0] and the eight bits of the lower byte are used for the mantissa. The default value of the mantissa is 00100000000 corresponding to 256 (decimal), corresponding to a divider ratio of 0.5. The maximum value of the mantissa is 512 corresponding to a divider ratio of 1. Note that the resolution of the VOUT_SCALE_LOOP command is 0.2%.

When PMBus commands are used to trim or margin the output voltage, the value of V_{REF} is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module can be adjusted with a minimum step size of 0.4% over a ±25% range from nominal using the VOUT_TRIM command over the PMBus.

The VOUT_TRIM command is used to apply a fixed offset voltage to the output voltage command value using the "Linear" mode with the exponent fixed at–10 (decimal). The value of the offset voltage is given by

$$V_{OUT(offset)} = VOUT_TRIM X 2^{-10}$$

This offset voltage is added to the voltage set through the divider ratio and nominal V_{REF} to produce the trimmed output voltage. The valid range in two's complement for this command is –4000h to 3FFFh. The high order two bits of the high byte must both be either 0 or 1. If a value outside of the +/-25% adjustment range is given with this command, the module will set it's output voltage to the nominal value (as if VOUT_TRIM had been set to 0), assert SMBALRT#, set the CML bit in STATUS_BYTE and the invalid data bit in STATUS_CML.

Output Voltage Margining Using the PMBus

The module can also have its output voltage margined via PMBus commands. The command VOUT_MARGIN_HIGH sets the margin high voltage, while the command VOUT_MARGIN_LOW sets the margin low voltage. Both the VOUT_MARGIN_HIGH and VOUT_MARGIN_LOW commands use the "Linear" mode with the exponent fixed at –10 (decimal). Two bytes are used for the mantissa with the upper bit [7] of the high byte fixed at 0. The actual margined output voltage is a combination of the VOUT_MARGIN_HIGH or VOUT_MARGIN_LOW and the VOUT_TRIM values as shown below

V_{OUT(MH)} = (VOUT_MARGIN_HIGH+ VOUT_TRIM) X 2⁻¹⁰

V_{OUT(ML)} = (VOUT_MARGIN_LOW+ VOUT_TRIM) X 2⁻¹⁰

Note that the sum of the margin and trim voltages cannot be outside the ±25% window around the nominal output voltage. The data associated with VOUT_MARGIN_HIGH and VOUT_MARGIN_LOW can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

The module is commanded to go to the margined high or low voltages using the OPERATION command. Bits [5:2] are used to enable margining as follows:

00XX: Margin Off

0101: Margin Low (Ignore Fault) 0110: Margin Low (Act on Fault) 1001: Margin High (Ignore Fault) 1010: Margin High (Act on Fault)

PMBus Adjustable Overcurrent Warning

The module can provide an overcurrent warning via the PMBus. The threshold for the overcurrent warning can be set using the parameter

IOUT_OC_WARN_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The exponent is fixed at –1 (decimal). The upper five bits of the mantissa are fixed at 0 while the lower six bits are programmable. Note that the actual value for IOUT_OC_WARN_LIMIT will vary from module to module due to calibration during production test,



PMBus Adjustable Overcurrent Warning (continued)

The value of the IOUT_OC_WARN_LIMIT can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

Temperature Status via PMBus

The module can provide information related to temperature of the module through the STATUS_TEMPERATURE command. The command returns information about whether the pre-set over temperature fault threshold and/or the warning threshold have been exceeded.

PMBus Adjustable Output Over and Under Voltage Protection

The module has output over and under voltage protection capability. The PMBus command VOUT_OV_FAULT_LIMIT is used to set the output over voltage threshold from four possible values: 108%, 110%, 112% or 115% of the commanded output voltage. The command VOUT_UV_FAULT_LIMIT sets the threshold that causes an output under voltage fault and can also be selected from four possible values: 92%, 90%, 88% or 85%. The default values are 112% and 88% of commanded output voltage. Both commands use two data bytes formatted as two's complement binary integers. The "Linear" mode is used with the exponent fixed to –10 (decimal) and the effective over or under voltage trip points given by:

V_{OUT(OV_REQ)} = (VOUT_OV_FAULT_LIMIT) X 2⁻¹⁰

 $V_{OUT(UV_REQ)} = (VOUT_UV_FAULT_LIMIT) \times 2^{-10}$

Values within the supported range for over and undervoltage detection thresholds will be set to the nearest fixed percentage. Note that the correct value for VOUT_SCALE_LOOP must be set in the module for the correct over or under voltage trip points to be calculated.

In addition to adjustable output voltage protection, the 6A Digital Pico SlimLynx Open Frame module can also be programmed for the response to the fault. The VOUT_OV_FAULT RESPONSE and VOUT_UV_FAULT_RESPONSE commands specify the response to the fault. Both these commands use a single data byte with the possible options as shown below.

- Continue operation without interruption (Bits [7:6] = 00, Bits [5:3] = xxx)
- 2. Continue for four switching cycles and then shut down if the fault is still present, followed by no restart or continuous restart (Bits [7:6] = 01, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart)

- 3. Immediate shut down followed by no restart or continuous restart (Bits [7:6] = 10, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart).
- 4. Module output is disabled when the fault is present and the output is enabled when the fault no longer exists (Bits [7:6] = 11, Bits [5:3] = xxx).

Note that separate response choices are possible for output over voltage or under voltage faults.

PMBus Adjustable Input Undervoltage Lockout

The module allows adjustment of the input under voltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold, while the VIN_OFF command sets the input voltage turn off threshold. For the VIN_ON command, possible values are 2.75V, and 3V to 14V in 0.5V steps. For the VIN_OFF command, possible values are 2.5V to 14V in 0.5V steps. If other values are entered for either command, they will be mapped to the closest of the allowed values.

VIN_ON must be set higher than VIN_OFF. Attempting to write either VIN_ON lower than VIN_OFF or VIN_OFF higher than VIN_ON results in the new value being rejected, SMBALERT being asserted along with the CML bit in STATUS_BYTE and the invalid data bit in STATUS CML.

Both the VIN_ON and VIN_OFF commands use the "Linear" format with two data bytes. The upper five bits represent the exponent (fixed at -2) and the remaining 11 bits represent the mantissa. For the mantissa, the four most significant bits are fixed at 0.

Power Good

The module provides a Power Good (PGOOD) signal that is implemented with an open-drain output to indicate that the output voltage is within the regulation limits of the power module. The PGOOD signal will be de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds.



Power Good (continued)

The PGOOD thresholds are user selectable via the PMBus (the default values are as shown in the Feature Specifications Section). Each threshold is set up symmetrically above and below the nominal value. The POWER_GOOD_ON command sets the output voltage level above which PGOOD is asserted (lower threshold). For example, with a 1.2V nominal output voltage, the POWER_GOOD_ON threshold can set the lower threshold to 1.14 or 1.1V. Doing this will automatically set the upper thresholds to 1.26 or 1.3V. The POWER_GOOD_OFF command sets the level below which the PGOOD command is de-asserted. This command also sets two thresholds symmetrically placed around the nominal output voltage. Normally, the POWER_GOOD_ON threshold is set higher than the POWER_GOOD_OFF threshold.

Both POWER_GOOD_ON and POWER_GOOD_OFF commands use the "Linear" format with the exponent fixed at -10 (decimal). The two thresholds are given by

 $V_{OUT(PGOOD_ON)} = (POWER_GOOD_ON) \times 2^{-10}$

V_{OUT(PGOOD OFF)} = (POWER_GOOD_OFF) X 2⁻¹⁰

Both commands use two data bytes with bit [7] of the high byte fixed at 0, while the remaining bits are r/w and used to set the mantissa using two's complement representation. Both commands also use the VOUT_SCALE_LOOP parameter so it must be set correctly. The default value of POWER_GOOD_ON is set at 1.1035V and that of the POWER_GOOD_OFF is set at 1.08V. The values associated with these commands can be stored in non-volatile memory using the STORE_DEFAULT_ALL command.

The PGOOD terminal can be connected through a pullup resistor (suggested value 100K Ω) to a source of 5V_{DC} or lower.

Measurement of Output Current, Output Voltage and Input Voltage

The module is capable of measuring key module parameters such as output current and voltage and input voltage and providing this information through the PMBus interface. Roughly every 200µs, the module makes 16 measurements each of output current, voltage and input voltage. Average values of of these 16 measurements are then calculated and placed in the appropriate registers. The values in the registers can then be read using the PMBus interface.

Measuring Output Current Using the PMBus

The module measures current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then the current gain factor used to scale the measured voltage into a current reading. This gain factor is the argument of the IOUT_CAL_GAIN command, and consists of two bytes in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –15 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT_CAL_OFFSET command is used to store and read the current offset. The argument for this command consists of two bytes composed of a 5-bit exponent (fixed at -4d) and a 11-bit mantissa. This command has a resolution of 62.5mA and a range of -4000mA to +3937.5mA. During manufacture, each module is calibrated by measuring and storing the current gain factor and offset into non-volatile storage.

The READ_IOUT command provides module average output current information. This command only supports positive or current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ_IOUT command returns two bytes of data in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at – 4 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa with the 11th bit fixed at 0 since only positive numbers are considered valid.

Note that the current reading provided by the module is not corrected for temperature. The temperature corrected current reading for module temperature T_{Module} can be estimated using the following equation

 $I_{OUT,CORR} = \frac{I_{REAR_OUT}}{1+[(T_{IND}-30) \times 0.00393]}$



Measuring Output Current Using the PMBus (continued)

where $I_{\text{OUT_CORR}}$ is the temperature corrected value of the current measurement, $I_{\text{READ_OUT}}$ is the module current measurement value, TIND is the temperature of the inductor winding on the module. Since it may be difficult to measure T_{IND} , it may be approximated by an estimate of the module temperature.

Measuring Output Voltage Using the PMBus

The module can provide output voltage information using the READ_VOUT command. The command returns two bytes of data all representing the mantissa while the exponent is fixed at -10 (decimal).

During manufacture of the module, offset and gain correction values are written into the non-volatile memory of the module. The command VOUT_CAL_OFFSET can be used to read and/or write the offset (two bytes consisting of a 16- bit mantissa in two's complement format) while the exponent is always fixed at -10 (decimal). The allowed range for this offset correction is -125 to 124mV. The command

offset correction is -125 to 124mV. The command VOUT_CAL_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a 11-bit mantissa. The range of this correction factor is -0.125V to +0.121V, with a resolution of 0.004V. The corrected output voltage reading is then given by:

V_{OUT} Final = [V_{OUT} (Initial) X (1 + VOUT_CAL_GAIN)] + VOUT_CAL_OFFSET

Measuring Input Voltage Using the PMBus

The module can provide output voltage information using the READ_VIN command. The command returns two bytes of data in the linear format. The upper five bits [7:3] of the high data form the two's complement representation of the exponent which is fixed at –5 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid.

During module manufacture, offset and gain correction values are written into the non-volatile memory of the module. The command VIN_CAL_OFFSET can be used to read and/or write the offset - two bytes consisting of a five-bit exponent (fixed at -5) and all-bit mantissa in two's complement format. The allowed range for this offset correction is -2 to 1.968V, and the resolution is 32mV. The command VIN_CAL_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a ll-bit mantissa. The range of this correction factor is -0.125V to +0.121V, with a resolution of 0.004V. The corrected output voltage reading is then given by:

 V_{IN} Final = [V_{IN} (Initial) X (1 + VIN_CAL_GAIN)] + VIN_CAL_OFFSET

Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. However, not all features are supported in these commands. A 1 in the bit position indicates the fault that is flagged.

STATUS_BYTE: Returns one byte of information with a summary of the most critical device faults.

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	V _{o∪T} Overvoltage	0
4	I _{OUT} Overcurrent	0
3	V _{IN} Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	V _{OUT} Overvoltage	0
4	I _{OUT} Overcurrent	0
3	V _{IN} Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

Low Byte

Bit Position	Flag	Default Value
7	V _{o∪T} fault or warning	0
6	Iou⊤ fault for warning	0
5	X	0
4	X	0
3	Power_GOOD# (is negated)	0
2	X	0
1	X	0
0	X	0

HighByte



Reading the Status of the Module using the PMBus (continued)

STATUS_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	Χ	0
5	Χ	0
4	VOUT UV Fault	0
3	Χ	0
2	Χ	0
1	X	0
0	Χ	0

STATUS_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	X	0
5	IOUT OC Warning	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	Χ	0
4	Χ	0
3	Χ	0
2	Χ	0
1	X	0
0	X	0

STATUS_CML: Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Command	0
5	Packet Error Check Failed	0
4	X	0
3	X	0
2	X	0
1	Other Communication Fault	0
0	X	0

MFR_VIN_MIN: Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12)

MFR_VOUT_MIN: Returns minimum output voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format fixed at 614)

MFR_SPECIFIC_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (000111 corresponds to the PxDT006 series of module), while bits [7:3] indicate the revision number of the module.

Bit Position	Flag	Default Value
7:2	Module Name	000111
1:0	Reserved	XX

Low Byte

Bit Position	Flag	Default Value
7:3	Module Revision Number	None
2:0	Reserved	XXX

High Byte



Summary of Supported PMBus Commands

Please refer to the PMBus 1.1 specification for more details of these commands.

Hex Code	Command	Brief Description									Non-Volatile Memory Storage	
		Turn Module o	n or o	ff. Also	used to	o marg	in the	outp	ut vol	ltage		
		Format			Uns	signed	Bina	ry				
01	ODEDATION	Bit Position	7	6	5	4	3	2	1	0		
01	OPERATION	Access	r/w	r	r/w	r/w	r/w	r/w	r	r		
		Function	On	Х	ļ.,	Marg		1	X	Χ		
		Default Value	0	0	0	0	0	0	Χ	Х	-	
		Configures the analog ON/OF						binati	on of			
		Format			Uns	signed	Binar	У				
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0	YES	
		Access r r r r/w r/w r/w r/w r										
	Function X X X pu cmd cpr pol cpa											
		Default Value	0	0	0	1	0	1	1	1		
03	CLEAR_FAULTS	Clear any fault SMBALERT# si								he		
		current registe matches the va	Jsed to control writing to the module via PMBus. Copies the current register setting in the module whose command code matches the value in the data byte into non-volatile memory EEPROM) on the module									
		Format			Uns	igned	Binar	У				
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	Χ	Χ	Χ	Χ	Χ		
		Function	bit7	bit6	bit5	Χ	Χ	Χ	Χ	Χ		
		Default Value	0	0	0	Χ	Χ	Χ	Χ	Х		
10	WRITE_PROTECT	Bit5: 0 – Enable 1 – Disable OPERATION ar ON_OFF. Bit 6: 0 – Enable 1 – Disable OPERATION commar Bit7: 0 – Enable 1 – Disable commar	les all nd _CON les all les all nds (bi es all les all nd (bit	writes FIG (b writes writes it5 and writes writes	it 6 and as perresected bit7 mass perresected bit6 must	the W bit7 m nitted for the ust be nitted for the ust be (RITE_ ust be in bit5 WRIT 0) in bit5 WRIT))	PROT e 0) f or bit fe_pr for bit fe_pr	ECT, t7 OTEC t6	CT	YES	
11	STORE_DEFAULT_ALL	Copies all current register settings in the module into non-volatile memory (EEPROM) on the module. Takes about 50ms for the command to execute.										
12	RESTORE_DEFAULT_ALL	Restores all cu in the module	non-v	olatile/	memo	ry (EEF	PROM)		values		
13	STORE_DEFAULT_CODE	Copies the cur command cod volatile memo Bit Position Access	le mat	tches t	the valu	e in th	e data			on-		
		Function		1 **		mman			**			



Summary of Supported PMBus Commands (continued)

Hex Code	Command			Brie	f Desc	criptio	n				Non-Volatile Memory Storage
14	RESTORE_DEFAULT_CODE	Restores the cu command cod value in the mo	e ma odule	tches t non-v	he val olatile	ue in th memo	ne data ry (EEF	byte PROM	from 1)	the	
		Bit Position Access Function	7 W	6 W	5 W	4 W omman	w nd Code	2 W e	l W	o W	
		The module ha These values ca	annot	t be ch	anged		-		set to		
20	VOUT_MODE	Access Function	7 r	f Mode	5 r	4	r Exp	r coner	r nt	r	
		Default Value Apply a fixed o		0 voltage			0 it volta	1 ige co	1 mma		
		value. Exponer Format		Linea	ar, two	's com	pleme	ent bi			
22	VOUT_TRIM	Bit Position Access Function	7 r/w	6 r/w	5 r/w	r/w High	r/w Byte	r/w	r/w	o r/w	YES
		Default Value Bit Position Access	0 7 r/w	0 6 r/w	0 5 r/w	0 4 r/w	0 3 r/w	0 2 r/w	0 1 r/w	0 0 r/w	
		Function Default Value	0	0	0	Low E	0	0	0	0	
		Sets the target Exponent is fix (VOUT_MARGII	ed at	-10. The	e offse	t is		out niç	gn.		
25	VOLIT MARCIN LIIGH	Format Bit Position Access	7 r	Linea 6 r/w	5 r/w	o's com 4 r/w	r/w	ent bi 2 r/w	nary 1 r/w	O r/w	\/FC
25	VOUT_MARGIN_HIGH	Function Default Value Bit Position	0	0	0 5	High 0	Byte 0 3	1 2	0	1 0	YES
		Access Function	r/w	r/w	r/w	r/w Low E	r/w Byte	r/w	r/w	r/w	
		Default Value Sets the target is fixed at -10. T	volta								
		×2 ⁻¹⁰ Format				's com				,	
26	VOUT_MARGIN_LOW	Bit Position Access Function	7 r	6 r/w	5 r/w	4 r/w High I	3 r/w Bvte	2 r/w	1 r/w	O r/w	YES
		Default Value Bit Position Access	0 7	0 6 r/w	0 5 r/w	0 4 r/w	0 3	2	0	0	
		Function Default Value	r/w O	1///	0	Low E	r/w Byte 0	r/w O	r/w O	r/w 1	



Summary of Supported PMBus Commands (continued)

Hex Code	Command			Brie	ef Desc	criptio	n				Non-Volatile Memory Storage
		Sets the scaling								oack	
		resistor divider	ratio					` '	. ,		
		Format		Linea		's com			nary		
		Bit Position	7	6	5	4	3	2	1	0	
29	VOUT_SCALE_LOOP	Access Function	r	r	r xpone	r	r	r	r/w lantiss	r/w	YES
23	VOOT_SCALL_LOOT	Default Value	1	0	1	1	1	0	0	1	123
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function			1 0	Mant					
		Default Value	0	0	0	0	0	0	0	0	
		Sets the value This must be h			_						
		• 2.75V					,				
		• 3V to 18V ir	n incr	ement	s of 0.5	5V					
		Format		Line	ar. two	o's com	pleme	ent bi	narv		
		Bit Position	7	6	5	4	3	2	1	0	
35	VIN_ON	Access	r	r	r	r	r	r	r	r	YES
		Function		E	xpone	ent		M	1antis:	sa	
		Default Value	1	1	1	1	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access Function	r	r/w	r/w	r/w Mant	r/w	r/w	r/w	r/w	
		Default Value	0	0	0	0	1	0	1	1	
		Sets the value		ut volt	ane at	which	the m	odule	turns	off	
		This must be lo								5 011	
		• 2.5V to 17.5									
			• 111111								
		Format	7			o's com			nary	0	
		Bit Position Access	7 r	6 r	5 r	4 r	3 r	2 r	r	O r	
36	VIN_OFF	Function	'	l .	xpone	L	'		1antis:		YES
		Default Value	1	1	1	1	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w		r/w	r/w	r/w	r/w	
		Function				Mant					
		Default Value	0	0	0	0]	0		0	
		Returns the va				rection	term	used 1	to cor	rect	
		the measured	outpu	ut curre	ent						
		Format		Line	ar, two	o's com	pleme	ent bi	nary		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r/w	\
38	IOUT_CAL_GAIN	Function	7		xpone		1		1antis:	sa V	YES
		Default Value Bit Position	7	6	5	0	3	2	0	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	,	. , , , ,	. ,	Mant		. ,	. ,	, ,	
		Default Value	\	√: Varia	ıble ba	ised on		y calik	oratio	n	
	l										

PNDT006_DS



Summary of Supported PMBus Commands (continued)

Hex Code	Command	Brief Description	Non-Volatile Memory Storage
		Returns the value of the offset correction term used to correct the measured output current	
		Format Linear, two's complement binary	
		Bit Position 7 6 5 4 3 2 1 0	
		Access r r r r r r/w r r	
39	IOUT_CAL_OFFSET	Function Exponent Mantissa Default Value 1 1 1 0 0 V 0 0	YES
		Bit Position 7 6 5 4 3 2 1 0	
		Access r r r/w r/w r/w r/w r/w r/w	
		Function Mantissa Default Value 0 0 V: Variable based on factory	
		Default Value 0 0 v. Variable based of factory calibration	
		Sets the voltage level for an output overvoltage fault. Exponent	
		is fixed at-10. Four fixed percentages of 108%, 110%, 112% and 115% are available	
		Format Linear, two's complement binary Bit Position 7 6 5 4 3 2 1 0	
/0	VOLIT OV FALILE LIMIT	Access r r/w r/w r/w r/w r/w r/w r/w r/w	VEC
40	VOUT_OV_FAULT_LIMIT	Function High Byte	YES
		Default Value 0 0 0 0 1 0 1 Bit Position 7 6 5 4 3 2 1 0	
		Bit Position 7 6 5 4 3 2 1 0 Access r/w r/w	
		Function Low Byte	
		Default Value 0 0 0 0 1 0 1 0	
41	VOUT_OV_FAULT _RESPONSE	Instructs the module on what action to take in response to an output overvoltage fault. The options are: RSP[1:0] 00- Module continues without interruption 01- Module continue s operation for 4 switching cycles and shuts down if fault persists 01- Module shuts down and responds to RS[2:0] 11 – Module shuts down and attempts to restart RS[2:0] 000 – Module does not attempt to restart 111- Module goes through normal startup continuously	YES
		Format Unsigned Binary Bit Position 7 6 5 4 3 2 1 0	
		Bit Position 7 6 5 4 3 2 1 0 Access r/w r/w r/w r/w r/w r r r r	
		Function RSP RSP ps[2] ps[1] ps[0] v v v	
		Tunction [1] [0] RS[2] RS[0] X X X X X X X X X	
		Sets the voltage level for an output undervoltage fault. Exponent is fixed at -10. Four fixed percentages of 92%, 90%,	
		88%and 85% are available.	
		FormatLinear, two's complement binaryBit Position76543210	
44	\/\C \T\ \\/\F\\\\T\\\\\	Access r r/w r/w r/w r/w r/w r/w r/w r/w	YES
44	VOUT_UV_FAULT_LIMIT	Function High byte	YES
		Default Value 0 0 0 0 1 0 0 Bit Position 7 6 5 4 3 2 1 0	
		Access r/w r/w r/w r/w r/w r/w r/w r/w r/w	
		Function Low byte	
		Default Value 1 0 0 0 1 1 1 1 1	



Summary of Supported PMBus Commands (continued)

Instructs the module on what action to take in response to a output undervoltage fault.	Hex Code	Command			Brie	ef Desc	criptio	n				Non-Volatile Memory Storage
VOUT_UV_FAULT_RESPONSE Nodule shuts down if fault persists			output underv	oltage	e fault.	hat act	tion to	take in	resp	onse t	to a	
Shuts down if fault persists O2 Module shuts down and responds to RS[2:0] 1 - Module shuts down and responds to RS[2:0] 1 - Module shuts down and attempts to restart RS[2:0] O00 - Module does not attempt to restart RS[2:0] O00 - Module does not attempt to restart RS[2:0] O00 - Module does not attempt to restart RS[2:0] O00 - Module does not attempt to restart RS[2:0] O00 - Module does not attempt to restart O00 - Module			02 Module cor	ntinue	s with	out int	terrupt	ion				
1 - Module shuts down and attempts to restart RS[2:0] O00 - Module does not attempt to restart Nodule goes through normal startup continuously. Format Unsigned Binary Bit Position 7 6 5 4 3 2 1 0 O O O O O O O O O							for 4 s	witchin	ng cyc	les an	nd	
## RESPONSE ROLL												
Module does not attempt to restart	45		RS[2:0]									YES
Format Unsigned Binary		RESPONSE	000 – Module	does r	not atte	empt t	o resta	rt				
Bit Position 7 6 5 4 3 2 1 0 Access r/w r/w r/w r/w r/w r/w r r r r Function RSP RSP RSI RS[0] x x x Default Value 1 1 1 1 1 1 0 0 Sets the output overcurrent fault level in A (cannot be changed) Format			111- Module g	goes tl	nrough	n norm	nal star	tup coi	ntinu	ously.		
Bit Position 7 6 5 4 3 2 1 0 Access r/w r/w r/w r/w r/w r/w r r r r Function RSP R			Format			Un	signe	d Binar	У			
Function RSP RSP RS[2] RS[1] RS[0] x x x x			Bit Position		_	5	4	3		1	0	
Function [i] [i] [i] RS 2 RS 1 RS 0 X X X X Default Value 1 1 1 1 1 1 1 0 0 0			Access			r/w	r/w	r/w	r	r	r	
Default Value			Function			RS[2]	RS[1]	RS[0]	Х	X	Х	
Changed Format Linear, two's complement binary			Default Value	1	1	1	1	1	1	0	0	
Bit Position 7 6 5 4 3 2 1 0 Access r r r r r r r r Function Exponent Mantissa Default Value 1 1 1 1 1 0 0 0 Bit Position 7 6 5 4 3 2 1 0 Access r r r r r r r r r			changed)	t over								
Access r r r r r r r r r				7							0	
Function Exponent Mantissa YES											_	
Bit Position 7 6 5 4 3 2 1 0 Access r r r r r r r r Function Mantissa Default Value 0 0 0 1 0 0 1 0 Sets the output overcurrent warning level in A	46	IOUT_OC_FAULT_LIMIT					ent			1antis:		YES
Access r r r r r r r r r r r Function				1	1	1	1	1				
Function												
Default Value				ı	ļ				ı	ı		
Format Linear, two's complement binary				0	0	0	1		0	1	0	
Format Linear, two's complement binary			Sets the outpu	t over	currer	nt warr	nina lev	/el in A				
Bit Position 7 6 5 4 3 2 1 0			· ·							narv		
Function Exponent Mantissa Default Value 1 1 1 1 0 0 0 Bit Position 7 6 5 4 3 2 1 0 Access r r r/w				7						1	0	
4A IOUT_OC_WARN_LIMIT Default Value 1 1 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0				r				r		1		
Bit Position 7 6 5 4 3 2 1 0 Access r r r r/w r/w r/w r/w r/w r/w Function Mantissa	4A	IOUT_OC_WARN LIMIT		1	1	xpone	ent I i	1				YES
Access r r r/w r/w r/w r/w r/w r/w Function Mantissa				7	6	5	4	3	-		_	
Function Mantissa											_	
Default Value 0 0 0 1 0 0 0												
			Default Value	0	0	0	1	0	0	0	0	



Summary of Supported PMBus Commands (continued)

Hex Code	Command			Brie	ef Desc	cription	n				Non-Volatile Memory Storage	
		Sets the outpu asserted high.					ne PG(DOD p	oin is			
		Format		Linea	ar, two	's com	plem	ent bi	nary			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				High						
		Default Value	0	0	0	0	0	1	0	0		
	50,4/55, 60,65, 64,	Bit Position	7	6	5	4	3	2	1	0	\/50	
5E	POWER_GOOD_ON	Access Function	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	YES	
		Default Value	0	l 1	1	Low k	Jyte I 1	0	1	0		
		Delault value		<u> </u>		U	'		'	1 0		
		POWER_GOOI	D_ON	LEVEL	.S							
		LOW HIGH										
		95% 105%										
		92% 108%										
		90% 110%	t volt	ago lov	ol at w	hich th	oo DC(oin ic			
			Sets the output voltage level at which the PGOOD pin is de-asserted low. Exponent is fixed at -10.									
			vv. L^									
		Format				's com	_		nary			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				High						
		Default Value Bit Position	7	0 6	5	0 4	3	2	0	0		
5F	POWER_GOOD_OFF	Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	YES	
	10112120002011	Function	1/ ۷۷	1/ ۷۷	17 00	Low k		1/ ۷۷	1/ ۷۷	1/ ۷۷	120	
		Default Value	0	1	0	1	0	0	1	0		
				/ -							J	
		POWER_GOOI	J_OFI	- LEVE	LS							
		LOW HIGH										
		92% 108%										
		90% 110%										
		88% 112%										
		Sets the rise tir	me of	the ou	tput v	oltage	during	start	up.			
		Supported valu	ues ar	e 0.6m	s, 0.9n	ns, 1.2m	ns, 1.8n	ns, 2.7	ms, 4.	.2ms,		
		6.0ms, 9.0ms										
		Format		Linea	ar, two	's com	plem	ent bi	nary			
		Bit Position	7	6	5	4	3	2	1	0		
Cl	TON DISE	Access	r	r	r	r	r	r	r	r/w	VEC	
61	TON_RISE	Function		E	xpone	nt			1antis	sa	YES	
		Default Value	1	1	1	0	0	0	0	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function			1 1	Mant	ıssa	1 0	l ,	1 7		
		Default Value	0	0		0		0	1			



Summary of Supported PMBus Commands (continued)

Hex Code	Command			Br	ief Do	escript	ion				Non-Volati Memory Stor
		Returns one by critical module			ation	with a	summa	ary of	the n	nost	
		Format					ed Bina				
78	STATUS_BYTE	Bit Position	7	6	5	4	3	2	1	0	-
		Access	r	r	r V _{OUT}	r	r	r	r	r	1
		Flag	Х	OFF	_OV		V_{IN_UV} T				
		Default Value	0	0	0	0	0	0	0	0	
		Returns two by fault/warning			natio	n with	a summ	nary o	fthe	module's	
		Format				Unsigr	ned Bina	ary			
		Bit Position	7	6	5	4	3	2	1	0	_
		Access	r	r	R	r	r	r	r	r	
79	STATUS_WORD	Function		I OUT_OC			PGOOD		X		_
		Default Value Bit Position	7	0 6	5	0 4	0	0	0	0	_
		Access	r	r	r	r	r	r	r	r	
		Flag	X	OFF	V _{OUT}		V _{IN_UV}			L OTHER	2
		Default Value	0	0	0	0	0	0	0	0	
		Returns one by output voltage				with t	he statu	is of th	ne m	odule's	
		Format					ed Bina				
7A	STATUS_VOUT	Bit Position Access	7 r	6 r		5 r	4 3 r r	_		1 0 r r	
		Flag	Vout				OUT_UV X			(X	
		Default Value	2 0	0		0	0 0				
		Returns one by output current				with t	he statu	is of th	ne m	odule's	
		Format				Unsigr	ned Bina	ary			
7B	STATUS_IOUT	Bit Position	7	6			4 3	2		I 0	
/ D	31A1U3_IUU1	Access	r	r	1	· I	r r	r		r r	
		Flag	I _{OUT_}	oc X			× ×	X	>	< x	
		Default Value		0	_w	arn () 0	0	() 0	
		Returns one by	yte of	inform	ation				ı.		
		Format				Insign	ed Bina	rv			
7D	STATUS_TEMPERATURE	Bit Position	7	,	6	Jnsign 5		3	2	1 0	
, 0	51/XI OS_I LIVIF LKATOKL	Access	r		r	r		r	r	r r	
		Flag		AILTO				Χ	Χ	X X	
		Default Value	С)	0	С	0	0	0	0 0	



Summary of Supported PMBus Commands (continued)

Hex Code	Command			Brief	Des	cripti	on					Non-Volatile Memory Storage
		Returns one byte communication			n wit	h the	stat	us of	the r	nodule	e's	
		Format			Ur	nsign	ed B	inary	,			
		Bit Position	7	(5	5	4	3	2	1	0	
7E	STATUS_CML	Access	r	1	ſ	r	r	r	r	r	r]
		Flag	Invalic Comma			PEC Fail	X	X	X	Othe Comr Faul	m X	
		Default Value	0)	0	0	0	0	0	0	1
		Returns the valu	a of the	innut	/Olta/	ne an	nliec	l to th	ne m	مليام		-
			ie oi tile	•		• .	•					
		Format		Linea		_				nary		
		Bit Position		6	5	4		3	2	<u> </u>	0	
		Access	r	r	r	r		r	r	r	r	
88	READ_VIN	Function Default Value	2 1	E	xpor 0	ient 1	1	1	0	1antiss 0	6 0	
		Bit Position	7	6	5	4		3	2	1	0	
		Access	/ r	r	r	r		r	r	r	r	
		Function	'	!			antis	•	'	ı	'	
		Default Value	e 0	0	0	1 0		0	0	0	0	
		Returns the valu fixed at -10.	ie of the	output	t volt	age c	of the	mod	dule. I	Expon	ent is	
		Format		Linea	r, tw	o's c	ompl	leme	nt bi	nary		
		Bit Position	7	6	5	4		3	2	1	0	
		Access	r	r	r	r		r	r	r	r	
8B	READ_VOUT	Function				Ma	ntiss	sa				
		Default Value		0	0	0		0	0	0	0	
		Bit Position	7	6	5	4		3	2	1	0	
		Access	r	r	r	r		r	r	r	r	
		Function					ntiss					
		Default Value	0	0	0	0		0	0	0	0	
		Returns the valu	e of the	output	t curi	rent c	of the	mod	dule			
		Format		Linea	r, tw	/o's c	omp	leme	nt bi	nary_		
		Bit Position	7	6	5	4		3	2]	0	
		Access	r	r	r	r		r	r	r	r	
8C	DEAD IOLIT	Function		E	kpon	ent			M	lantiss	sa	
OC	READ_IOUT	Default Value		1	1	0		0	0	0	0	
		Bit Position	7	6	5	4		3	2	1	0	
		Access	r	r	r	r		r	r	r	r	
		Function					ntiss					
		Default Value	9 0	0	0	0		0	0	0	0	
		Returns one byte Spec. 1.1 (read on		ting the	e mo	dule	is coi	mplia	nt to	РМВ	JS	
		Format			U	nsign	ed_B	inar	/			
98	PMBUS_REVISION	Bit Position	7	6	5	4	_	3	2	1	0	YES
		Access	r	r	r	r		r	r	r	r	
		Default Value		0	0	1		0	0	0	i	
		Doladic value		· ·		1 '	i	-		<u> </u>	•	



Summary of Supported PMBus Commands (continued)

Hex Code	Command			Brie	f Desc	cription	า				Non-Volatile Memory Storage
		Returns the mi operate at (rea			ut volta	age the	e mod	ule is:	specif	ied to	
		Format		Linea	ar, two	's com	plem	ent bi	nary		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
AO	MFR_VIN_MIN	Function		E	xpone	nt		1	1antis		YES
		Default Value	1	1	1	1	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function	0	0		Mant	ıssa	1			
		Default Value	0	0	0	0	l l		0	0	
		Returns the mi module (read o									
		Format				's com			nary		
		Bit Position	7	6	5	4	3	2		0	
A4	MFR VOUT MIN	Access Function	r	r	r	r Mant	l l	r	r	r	YES
A4	MFR_VOOT_MIN	Default Value	0	0	0	0	0	0	1	0	1 5
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function	·			Mant	issa	<u> </u>	<u>'</u>	1 .	
		Default Value	0	1	1	0	0	1	1	0	
		Returns modul	le nar			•	•				
		Format		Linea	ar, two	's com	plem	ent bi	nary		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
DO	MFR_SPECIFIC_00	Function		T		Reser	ved		1		YES
	M 1C31 E611 16_66	Default Value	Χ	Х	X	Х	X	Χ	Χ	X	123
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function			1	e Name	9	-		erved	
		Default Value	0	0	0	ı	l	I	Х	Χ	
		Applies an offsocalibrate out of output voltage fixed at -10.	ffset e	errors in veen -1	n mod I25mV	ule me and +1	asurer 24mV	ments). Exp	of the	е	
		Format				's com			nary		
		Bit Position	7	6	5	4	3	2	1	0	
D4	VOUT_CAL_OFFSET	Access	r/w	r	r	r	r	r	r	r	YES
		Function	V			Mant	1			0	
		Default Value Bit Position	7	0 6	5	0 4	3	0	0	0	
		Access	r/W	r/W	r/W	r/w	r/w	r/w	r/w	r/w	
		Function	1/ / /	1/ V V	1/ ۷ ۷	Mant		1/ ۷۷	1/ ۷۷	1 / ۷۷	
		Default Value	V	V	V	V	V	V	V	V	
						· •	ı	· ·	1		

Table 6 (continued)



Summary of Supported PMBus Commands (continued)

Hex Code	Command					criptio					Non-Volatile Memory Storage
		Applies a gain to calibrate ou output voltage	t gair	errors	in mo	dule m	easur				
		Format		Linea	ar, two	o's com	pleme	ent bi	nary		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r/w	
D5	VOUT_CAL_GAIN	Function		Е	xpone	ent		M	lantis	sa	YES
		Default Value	1	1	0	0	0	0	0	V	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/W	r/W	r/W	r/w	r/w	r/w	r/w	r/w	
		Function				Mant	issa				
		Default Value	V	V	V	V	V	V	V	V	
		Applies an offs to calibrate ou input voltage (t offse	et error een -2\	s in m / and -	odule r +1.968V	neasu)	reme	nts of		
		Format				o's com	_		nary		
		Bit Position	7	6	5	4	3	2	1	0	
D6	VIN CAL OFFSET	Access	r	r	r	r	r	r	r	r	YES
	VIIN_CAL_OTTSET	Function			xpone	ent -			1antis		123
		Default Value		1	0	l	V	0	0	V	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w	
		Function		1 0	1 ,,	Mant				1 ,,	
		Default Value	0	0	V	V	V	V	V	V	
		Applies a gain calibrate out g voltage (betwe	ain er	rors in 0.125 an	modu d 0.121	ıle mea I)	surem	nents (of the		
		Format		Linea		o's com	pleme		nary		
		Bit Position	7	6	5	4	3	2	1	0	
D7	VIN CAL GAIN	Access	r	r	r	r	r/w	r	r	r/w	YES
D/	VIII_CAL_GAIII	Function		E	xpone		1	_	antis		IES
		Default Value	1	1	0	0	V	0	0	V	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r/w	r/w	r/w	r/w	r/w	
		Function				Mant		1	1		
		Default Value	0	0	0	V	V	V	V	V	



Thermal Considerations

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 47. The preferred airflow direction for the module is in Figure 48.

Power Module

Power Module

76.2
(3.0)

Probe Location for measuring airflow and ambient temperature

Air flow

Figure 47. Thermal Test Setup.

The thermal reference points, T_{ref} used in the specifications are also shown in Figure 48. For reliable operation the temperatures at the Q1 and L1 should not exceed 130°C. The output power of the module should not exceed the rated power of the module (V_{o.set} x I_{o.max}).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

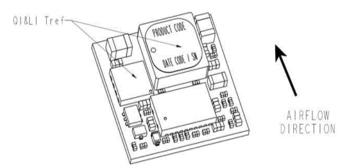


Figure 48. Preferred airflow direction and location of hot-spot of the module (Tref).



Example Application Circuit

Requirements:

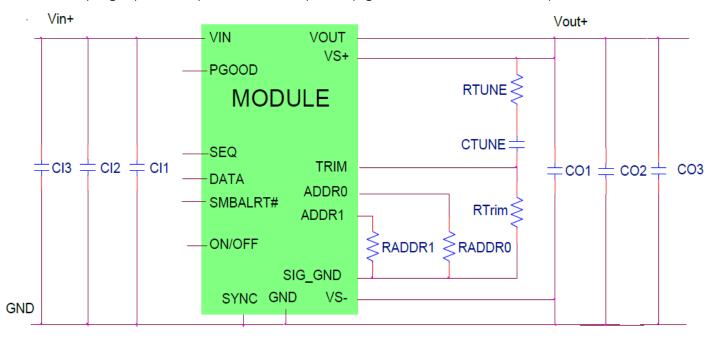
V_{in}: 12V V_{out}: 1.8V

I_{out}: 4.5A max., worst case load transient is from 3A to 4.5A

DV_{out}: 1.5% of V_{out} (27mV) for worst case load transient

 $V_{in, ripple}$ 1.5% of V_{in} (180mV, p-p)

CII Decoupling cap - 1x0.047µF/16V ceramic capacitor (e.g. Murata LLL185R71C473MA01)



CI2 2x22µF/16V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)

CI3 470µF/16V bulk electrolytic

CO1 Decoupling cap - 2x0.047µF/16V ceramic capacitor (e.g. Murata LLL185R71C473MA01)

CO2 3x47µF/16V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)

CO3 1x330µF/6V POSCAP

C_{Tune} 3900pF ceramic capacitor (can be 1206, 0805 or 0603 size)

 R_{Tune} 300 Ω SMT resistor (can be 1206, 0805 or 0603 size)

 R_{Trim} 10k Ω SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

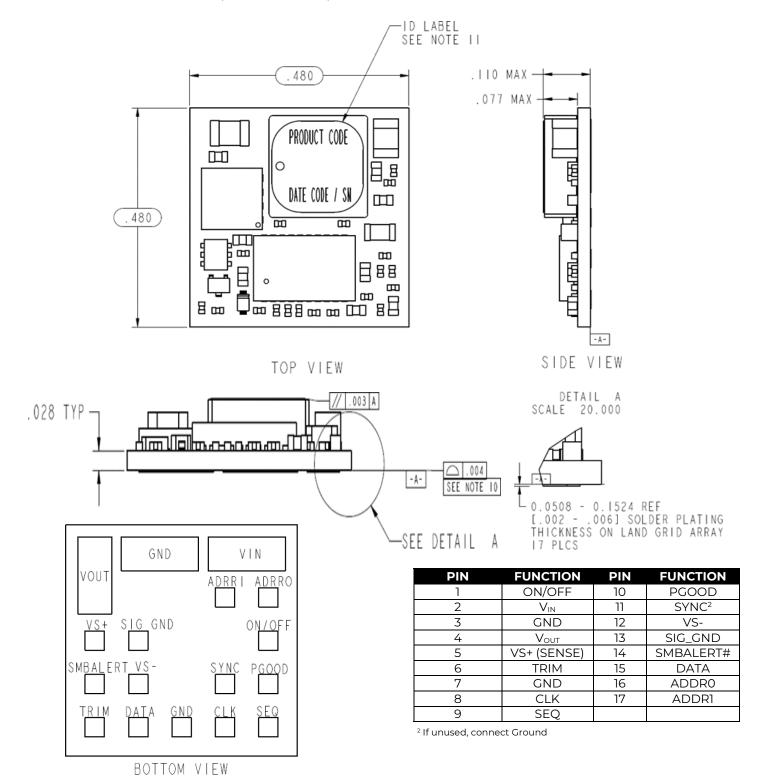
Note: The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the SMBus master controller will have the pull-up resistors as well as provide the driving source for these signals.



Mechanical Outline

Dimensions are in millimeters and (inches).

Tolerances: x.x mm ± 0.5 mm (x.xx in. ± 0.02 in.) [unless otherwise indicated] x.xx mm ± 0.25 mm (x.xxx in ± 0.010 in.)



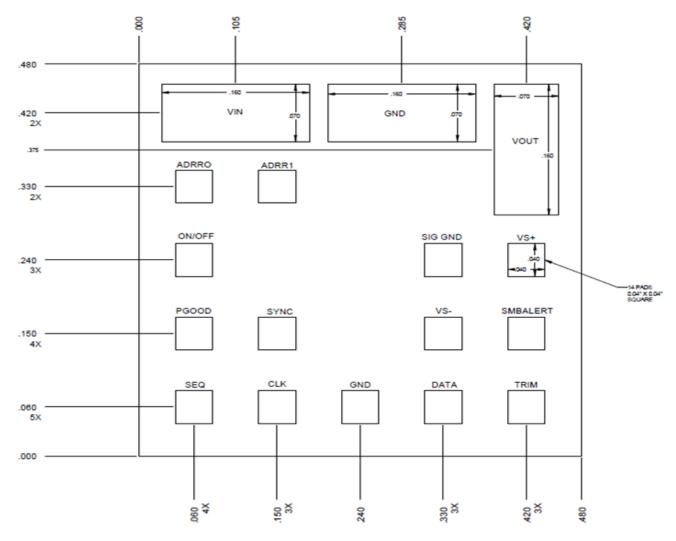
Page 37



Recommended Pad Layout

Dimensions are in millimeters and (inches).

Tolerances: x.x mm ± 0.5 mm (x.xx in. ± 0.02 in.) [unless otherwise indicated] x.xx mm ± 0.25 mm (x.xxx in ± 0.010 in.)



PIN	FUNCTION	PIN	FUNCTION
1	ON/OFF	10	PGOOD
2	V _{IN}	11	SYNC ²
3	GND	12	VS-
4	V _{OUT}	13	SIG_GND
5	VS+ (SENSE)	14	SMBALERT#
6	TRIM	15	DATA
7	GND	16	ADDR0
8	CLK	17	ADDRI
9	SEQ		

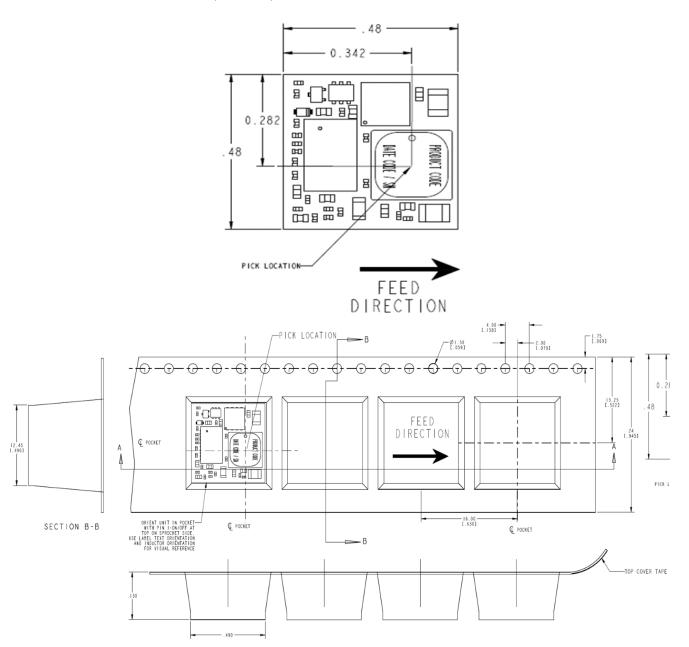
²If unused, connect to Ground.



Packaging Details

The 12V Digital Pico SlimLynx 6A Open Frame modules are supplied in tape & reel as standard. Modules are shipped in quantities of 500 modules per reel.

All Dimensions are in millimeters and (in inches).



Reel Dimensions:

Outside Dimensions: 254 mm (10.00) Inside Dimensions: 177.8 mm (7.00") Tape Width: 24.00 mm (0.945")



Surface Mount Information

Pick and Place

The 6A Digital Pico SlimLynx Open Frame modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

Nozzle Recommendations

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 3mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 7 mm.

Lead Free Soldering

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

Pb-free Reflow Profile

Power Systems will comply with J-STD-020 Rev. D (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 49. Soldering outside of the recommended profile requires testing to verify results and performance.

MSL Rating

The 6A Digital Pico SlimLynx Open Frame modules have a MSL rating of 2a.

Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/ Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of ≤ 30°C and 60% relative humidity

varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: < 40°C, < 90% relative humidity.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to Board Mounted Power Modules: Soldering and Cleaning Application Note (ANO4-001).

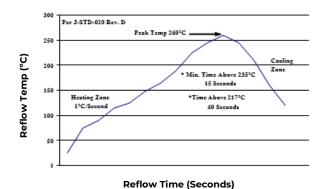


Figure 49. Recommended linear reflow profile using Sn/Ag/Cu solder



Ordering Information

Please contact your OmniOn Sales Representative for pricing, availability and optional features.

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Sequencing	Ordering Code
PNDT006A0X3-SRZ	3 – 14.4V _{dc}	0.45 – 5.5V _{dc}	6A	Negative	Yes	150039831

Table 9. Device Codes

⁻Z refers to RoHS compliant parts

Package Identifier	Family	Sequencing Option	Output current	Output voltage	On/Off logic	Remote Sense	Options	RoHS Compliance
Р	ND	T	006A0	X		3	-SR	Z
P=Pico U=Micro M=Mega G=Giga	ND=SlimLynx Digital Open Frame NV=SlimLynx Digital Open Frame	T=with EZ Sequence	6A	X = programmabl e output	No entry = negative	3 = Remote Sense	S = Surface Mount R = Tape & Reel	Z = RoHS6

Table 10 . Coding Scheme

OmniOn Power Electronics Inc.'s digital non-isolated DC-DC products may be covered by one or more of the following patents licensed from Bel Power Solutions, Inc.: US20040246754, US2004090219A1, US2004093533A1, US2004123164A1, US2004123167A1, US2004178780A1, US2004179382A1, US20050200344, US20050223252, US2005289373A1, US20060061214, US2006015616A1, US20060174145, US20070226526, US20070234095, US20070240000, US20080052551, US20080072080, US20080186006, US6741099, US6788036, US6936999, US6949916, US7000125, US7049798, US7068021, US7080265, US7249267, US7266709, US7315156, US7372682, US7373527, US7394445, US7456617, US7459892, US7493504, US7526660.

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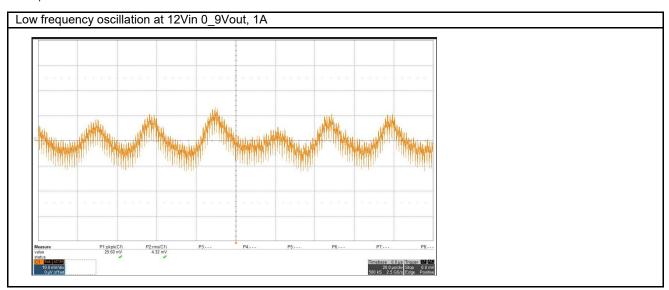
Errata

Known Exception to Functional Specifications

Output-voltage low frequency oscillation has been observed at following load conditions where Phase Margin dips below 45°, with no practical fix available.

Vout (V)	lout (<45° PM)
0.9	1A
1.1	1A
1.3	1A
1.5	1A
1.7	1A

Example:



This limitation causes no problem in most applications, but customers are cautioned to check for this behavior if expecting prolonged operation at light load for output voltages between 0.9V and 1.7V



Change History (excludes grammar & clarifications)

Revision	Date	Description of the change
14.3	12/09/2021	Updated as per template
14.4	12/8/2023	Updated as per OmniOn template
14.5	10/14/2024	Added ERRATA
14.6	11/19/2024	Update Trademark information



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